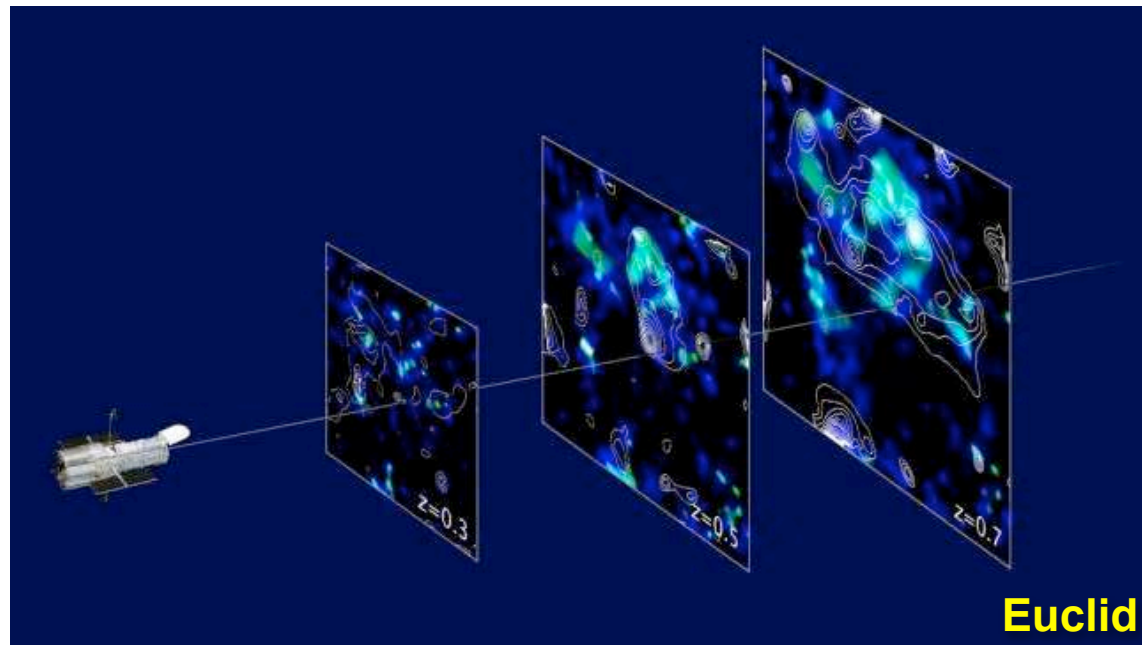


Sparsity in Astrophysics: from Wavelets to Compressed Sensing

J.-L. Starck



What is a good representation for data?

A signal s (n samples) can be represented as sum of weighted elements of a given dictionary

Dictionary (basis, frame)

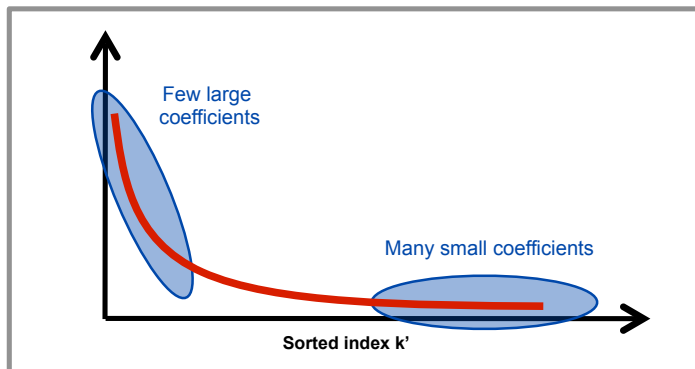
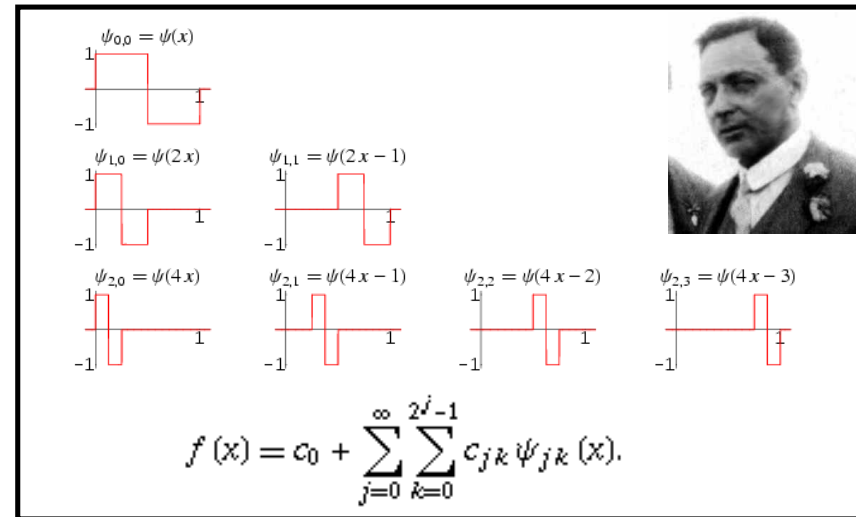
$$\Phi = \{\phi_1, \dots, \phi_K\}$$

Ex: Haar wavelet

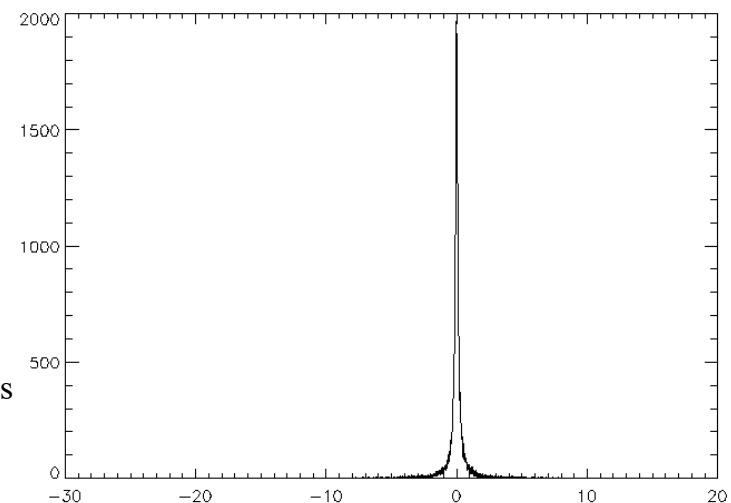
Atoms

$$s = \sum_{k=1}^K \alpha_k \phi_k = \Phi \alpha$$

coefficients

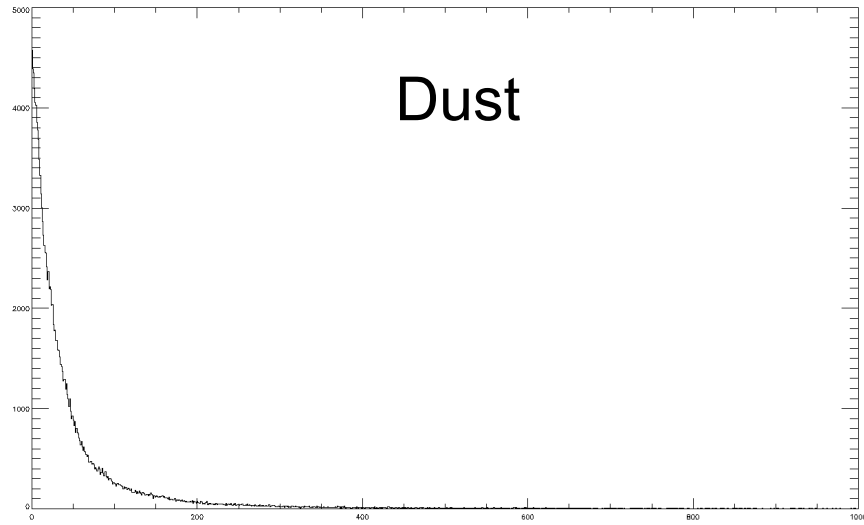


- Fast calculation of the coefficients
- Analyze the signal through the statistical properties of the coefficients
- Approximation theory uses the sparsity of the coefficients

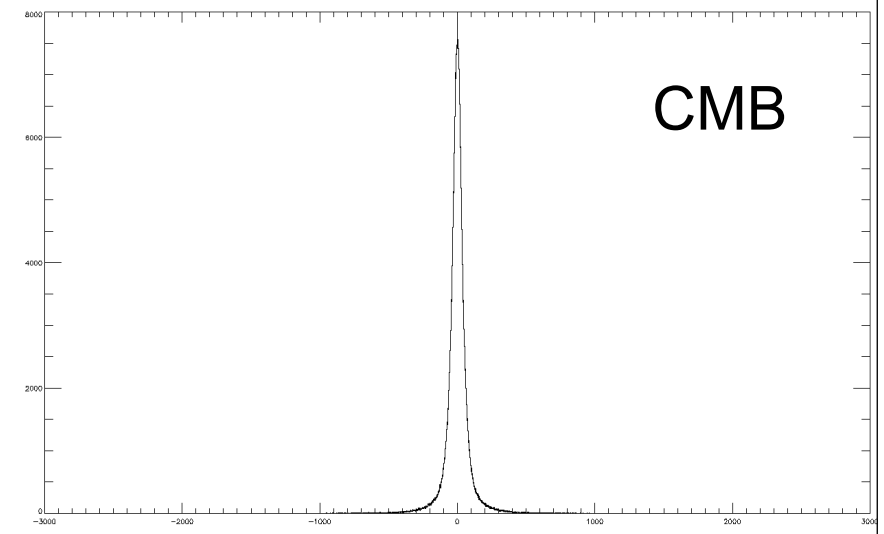
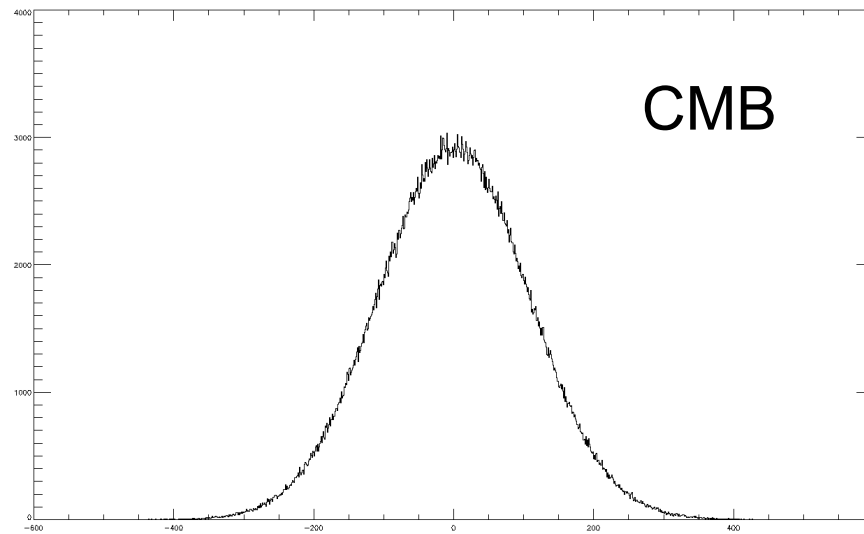
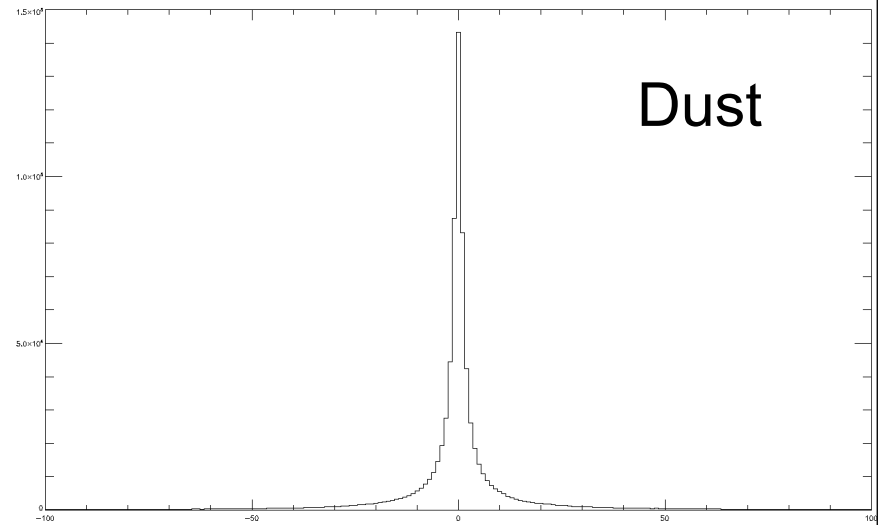


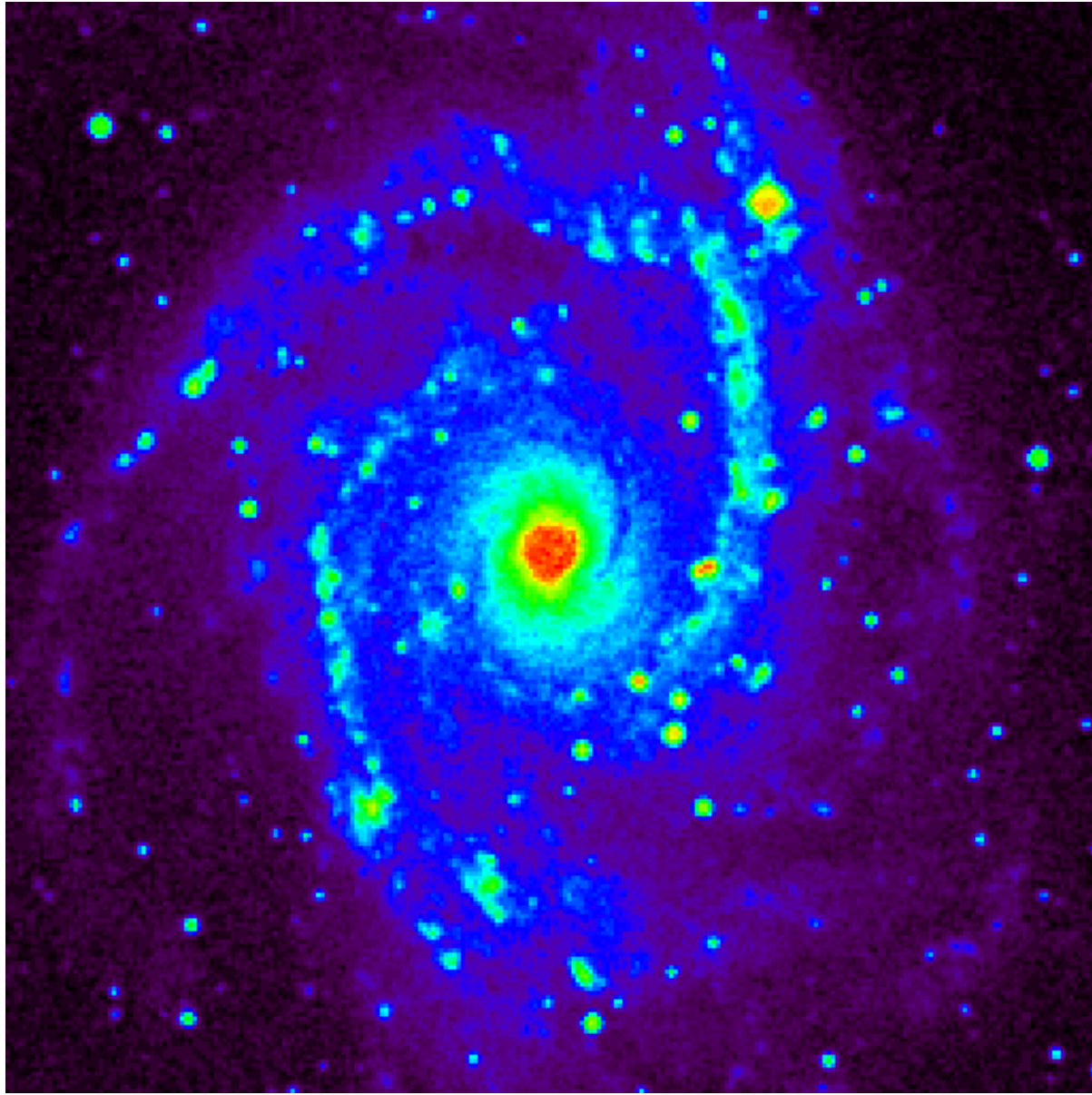
Histogram

Spatial Domain



Wavelet Domain





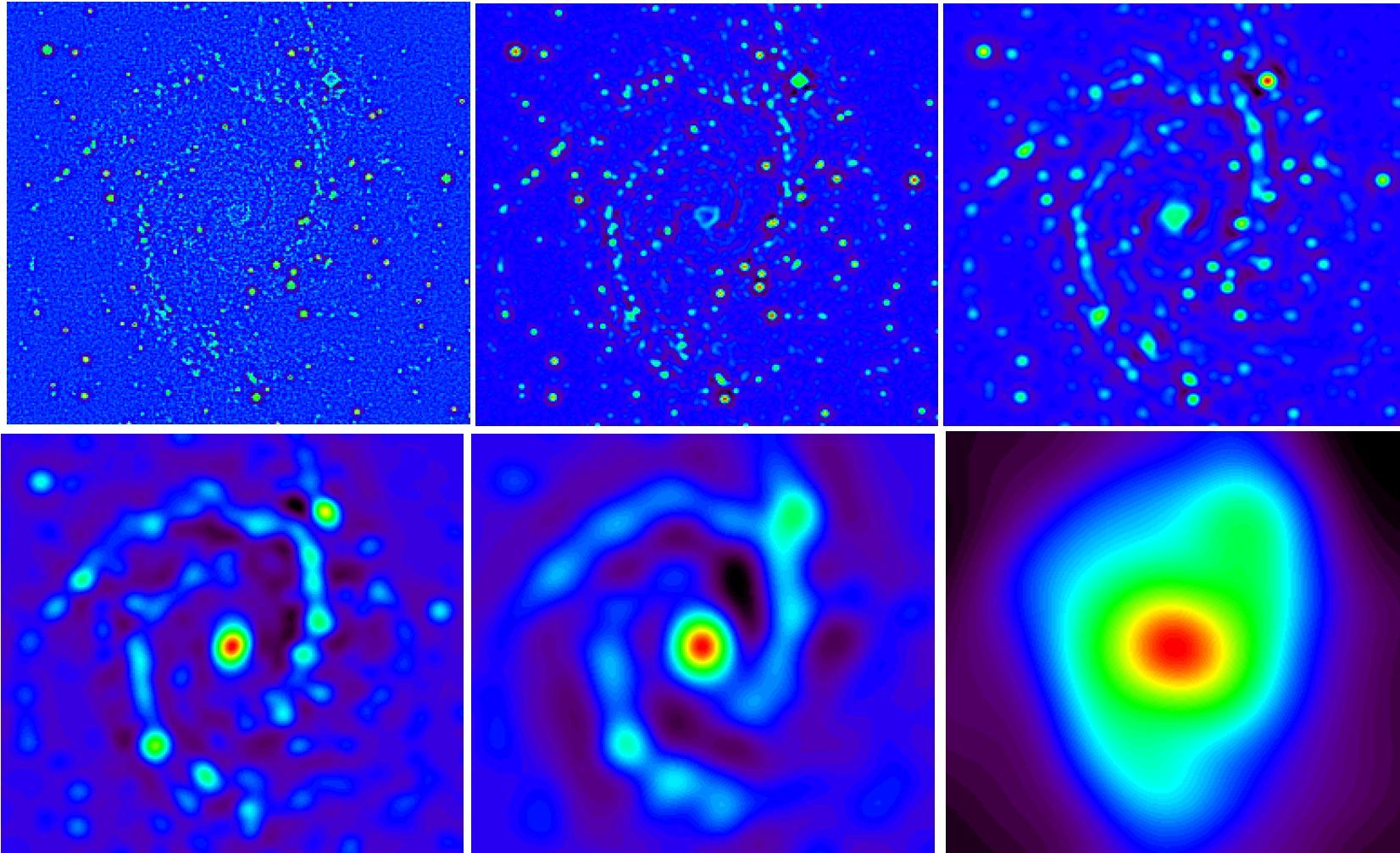
The STARLET Transform

Isotropic Undecimated Wavelet Transform (a trous algorithm)

$$\varphi = B_3 - \text{spline}, \quad \frac{1}{2}\psi\left(\frac{x}{2}\right) = \frac{1}{2}\varphi\left(\frac{x}{2}\right) - \varphi(x)$$

$$h = [1,4,6,4,1]/16, \quad g = \delta - h, \quad \tilde{h} = \tilde{g} = \delta$$

$$I(k,l) = c_{J,k,l} + \sum_{j=1}^J w_{j,k,l}$$



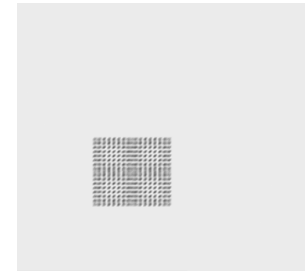
Sparsity Model 1: we consider a dictionary which has a fast transform/reconstruction operator:

$$\Phi = \{\phi_1, \dots, \phi_K\}$$

$$s = \sum_{k=1}^K \alpha_k \phi_k = \Phi \alpha$$

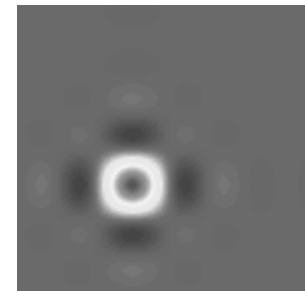
Local DCT

Stationary textures
Locally oscillatory



Wavelet transform

Piecewise smooth
Isotropic structures



Curvelet transform

Piecewise smooth,
edge



How to measure sparsity ?

$$\text{with } 0^0 = 0, \quad \|\alpha\|_0 = \sum_k \alpha_k^0 = \#\{\alpha_k \neq 0\}$$

Formally, the sparsest coefficients are obtained by solving the optimization problem:

$$(P0) \quad \text{Minimize } \|\alpha\|_0 \quad \text{subject to} \quad S = \phi\alpha$$

It has been proposed (*to relax and*) to replace the l_0 norm by the l_1 norm (Chen, 1995):

$$(P1) \quad \text{Minimize } \|\alpha\|_1 \quad \text{subject to} \quad S = \phi\alpha$$

It can be seen as a kind of convexification of (P0).

It has been shown (Donoho and Huo, 1999) that for certain dictionary, if there exists a highly sparse solution to (P0), then it is identical to the solution of (P1).



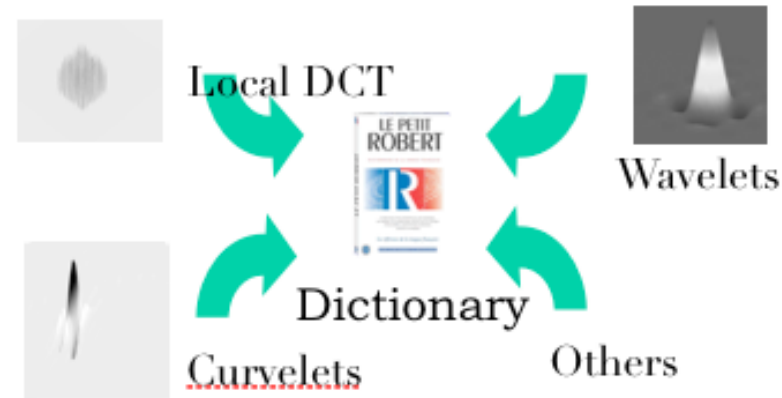
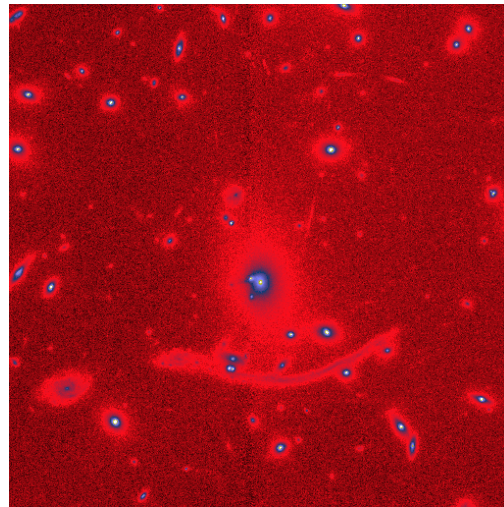
Morphological Diversity



*J.-L. Starck, M. Elad, and D.L. Donoho, *Redundant Multiscale Transforms and their Application for Morphological Component Analysis*, *Advances in Imaging and Electron Physics*, 132, 2004.

*J.-L. Starck, M. Elad, and D.L. Donoho, *Image Decomposition Via the Combination of Sparse Representation and a Variational Approach*, *IEEE Trans. on Image Proces.*, 14, 10, pp 1570--1582, 2005.

*J. Bobin et al, *Morphological Component Analysis: an adaptive thresholding strategy*, *IEEE Trans. on Image Processing*, Vol 16, No 11, pp 2675--2681, 2007.



$$\phi = [\phi_1, \dots, \phi_L], \quad \alpha = \{\alpha_1, \dots, \alpha_L\}, \quad s = \phi\alpha = \sum_{k=1}^L \phi_k \alpha_k$$

Sparsity Model 2: we consider a signal as a sum of K components s_k , $s = \sum_{k=1}^K s_k$ each of them being sparse in a given dictionary :

$$s_k = \Phi_k \alpha_k$$

$$s = \sum_{k=1}^K s_k = \sum_{k=1}^K \Phi_k \alpha_k = \Phi \alpha$$

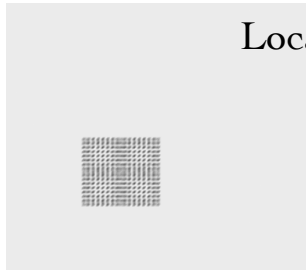


Sparsity Model 1: we consider a dictionary which has a fast transform/reconstruction operator:

$$\Phi = \{\phi_1, \dots, \phi_K\}$$

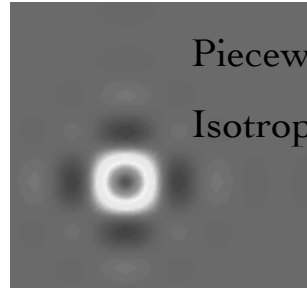
$$s = \sum_{k=1}^K \alpha_k \phi_k = \Phi \alpha$$

Local DCT Stationary textures



Locally oscillatory

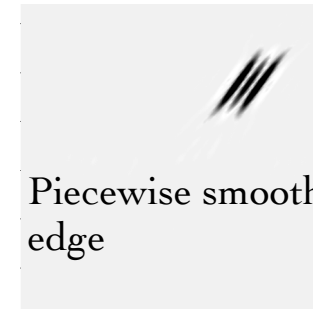
Wavelet transform



Piecewise smooth

Isotropic structures

Curvelet transform



Piecewise smooth, edge

Sparsity Model 2: Morphological Diversity:

$$\phi = [\phi_1, \dots, \phi_L], \quad \alpha = \{\alpha_1, \dots, \alpha_L\}, \quad s = \phi \alpha = \sum_{k=1}^L \phi_k \alpha_k$$

Sparsity Model 3: we adapt/learn the dictionary directly from the data

Model 3 can be also combined with model 2:



Advantages of model 1 (fixed dictionary) : extremely fast.

Advantages of model 2 (union of fixed dictionaries):

- more flexible to model 1.
- The coupling of local DCT+curvelet is well adapted to a relatively large class of images.

Advantages of model 3 (dictionary learning):

atoms can be obtained which are well adapted to the data, and which could never be obtained with a fixed dictionary.

Drawback of model 3 versus model 1,2:

We pay the price of dictionary learning by being less sensitive to detect very faint features.

Complexity: Computation time, parameters, etc

INVERSE PROBLEMS

$$Y = HX + N$$

$$X = \Phi\alpha, \text{ and } \alpha \text{ is sparse}$$

$$\min_{\alpha} \|\alpha\|_p^p \quad \text{subject to} \quad \|Y - H\Phi\alpha\|^2 \leq \epsilon$$

- Denoising
- Deconvolution
- Component Separation
- Inpainting
- Blind Source Separation
- Minimization algorithms
- Compressed Sensing

Denoising using a sparsity model

$$Y = X + N$$

Denoising using a sparsity prior on the solution:

X is sparse in Φ , i.e. $X = \Phi\alpha$ where most of α are negligible.

$$\tilde{\alpha} \in \arg \min_{\alpha} \frac{1}{2} \| Y - \Phi\alpha \|^2 + t \| \alpha \|_p^p, \quad 0 \leq p \leq 1.$$

$p=0$

$$\tilde{\alpha} \in \arg \min_{\alpha} \frac{1}{2} \| Y - \Phi \alpha \|^2 + \frac{t^2}{2} \| \alpha \|_0$$

\implies Solution via Iterative **Hard** Thresholding

$$\tilde{\alpha}^{(t+1)} = \text{HardThresh}_{\mu t}(\tilde{\alpha}^{(t)} + \mu \Phi^T (Y - \Phi \tilde{\alpha}^{(t)})), \mu = 1 / \|\Phi\|^2.$$

$$\tilde{\alpha}_{j,k} = \text{HardThresh}_t(\alpha_{j,k}) = \begin{cases} \alpha_{j,k} & \text{if } |\alpha_{j,k}| \geq t, \\ 0 & \text{otherwise.} \end{cases}$$

1st iteration solution:

$$\tilde{X} = \Phi \text{HardThresh}_t(\Phi^T Y) = \Delta_{\Phi,t}(Y)$$

Exact for Φ orthonormal.

$p=1$

$$\tilde{\alpha} = \arg \min_{\alpha} \frac{1}{2} \| Y - \Phi \alpha \|^2 + t \| \alpha \|_1$$

==> Solution via iterative **Soft** Thresholding

$$\tilde{\alpha}^{(t+1)} = \text{SoftThresh}_{\mu t}(\tilde{\alpha}^{(t)} + \mu \Phi^T (Y - \Phi \tilde{\alpha}^{(t)})), \mu \in (0, 2 / \|\Phi\|^2).$$

$$\tilde{\alpha}_{j,k} = \text{SoftThresh}_t(\alpha_{j,k}) = \text{sign}(\alpha_{j,k})(|\alpha_{j,k}| - t)_+$$

1st iteration solution:

$$\tilde{X} = \Phi \text{SoftThresh}_t(\Phi^T Y) = \Delta_{\Phi,t}(Y)$$

Exact for Φ orthonormal.

Inverse Problems and Iterative Thresholding Minimizing Algorithm

Iterative thresholding with a varying threshold was proposed in (Starck et al, 2004; Elad et al, 2005) for sparse signal decomposition in order to accelerate the convergence. The idea consists in using a different threshold $\lambda^{(n)}$ at each iteration.

$$\text{For IST: } \alpha^{(n+1)} = \text{HT}_{\lambda^{(n)}} \left(\alpha^{(n)} + \Phi^T A^T \left(Y - A\Phi\alpha^{(n)} \right) \right)$$

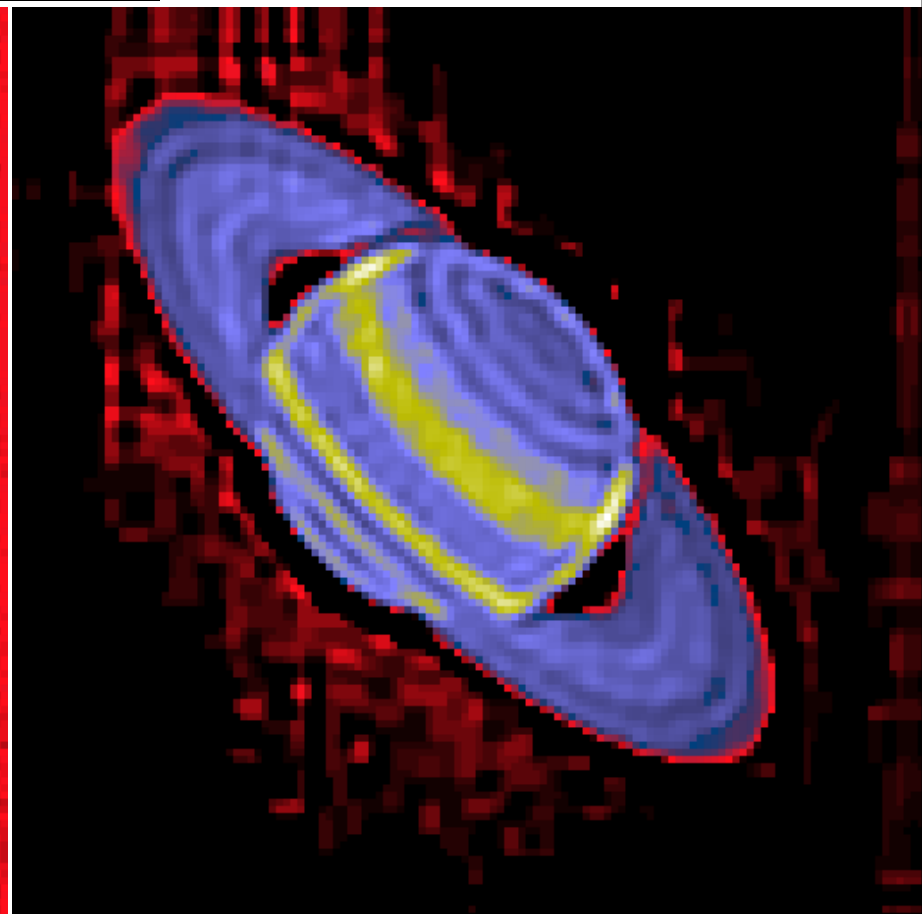
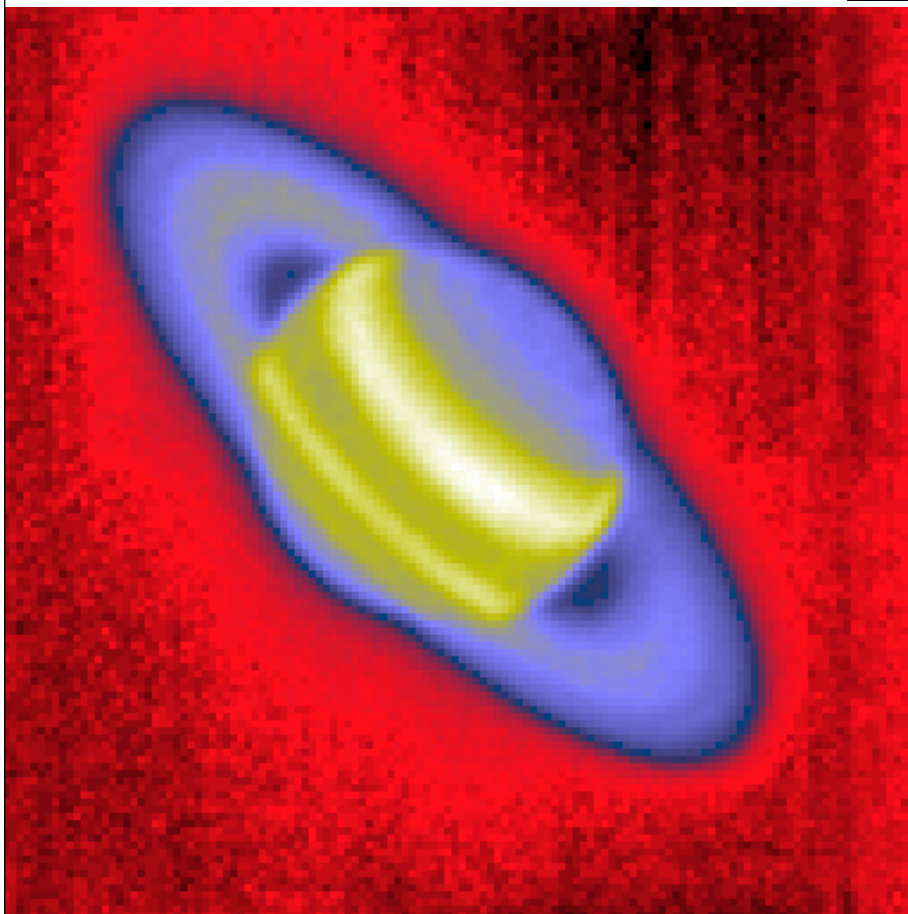
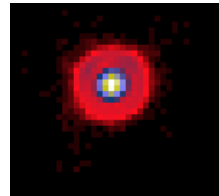
$$\text{For IHT: } \alpha^{(n+1)} = \text{ST}_{\lambda^{(n)}} \left(\alpha^{(n)} + \Phi^T A^T \left(Y - A\Phi\alpha^{(n)} \right) \right)$$

More Refs: Vonesch et al, 2007; Elad et al 2008; Wright et al., 2008; Nesterov, 2008 and Beck-Teboulle, 2009; Blumensath, 2008; Maleki et Donoho, 2009 ; Dupe et al, 2010; Dupe et al 2011; Geyre et al, 2011, etc.



DECONVOLUTION

- E. Pantin, J.-L. Starck, and F. Murtagh, "Deconvolution and Blind Deconvolution in Astronomy", in *Blind image deconvolution: theory and applications*, pp 277--317, 2007.
- J.-L. Starck, F. Murtagh, and M. Bertero, "The Starlet Transform in Astronomical Data Processing: Application to Source Detection and Image Deconvolution", Springer, *Handbook of Mathematical Methods in Imaging*, in press, 2010.





Compressed Sensing

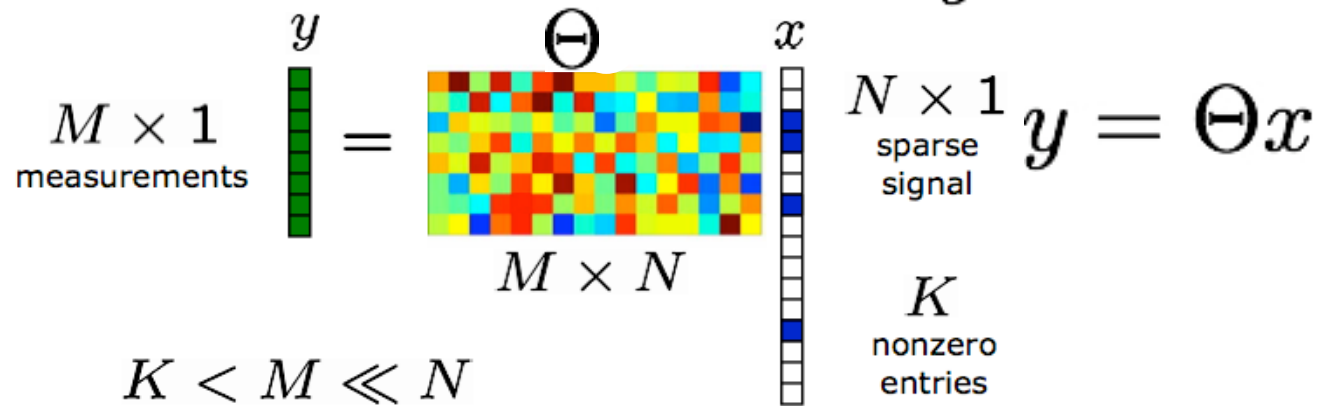


- * E. Candès and T. Tao, "Near Optimal Signal Recovery From Random Projections: Universal Encoding Strategies?", IEEE Trans. on Information Theory, 52, pp 5406–5425, 2006.
- * D. Donoho, "Compressed Sensing", IEEE Trans. on Information Theory, 52(4), pp. 1289–1306, April 2006.
- * E. Candès, J. Romberg and T. Tao, "Robust Uncertainty Principles: Exact Signal Reconstruction from Highly Incomplete Frequency Information", IEEE Trans. on Information Theory, 52(2) pp. 489 – 509, Feb. 2006.

A non linear sampling theorem

“Signals with exactly K components different from zero can be recovered perfectly from $\sim K \log N$ incoherent measurements”

Replace samples with *few linear projections* $y = \Theta x$

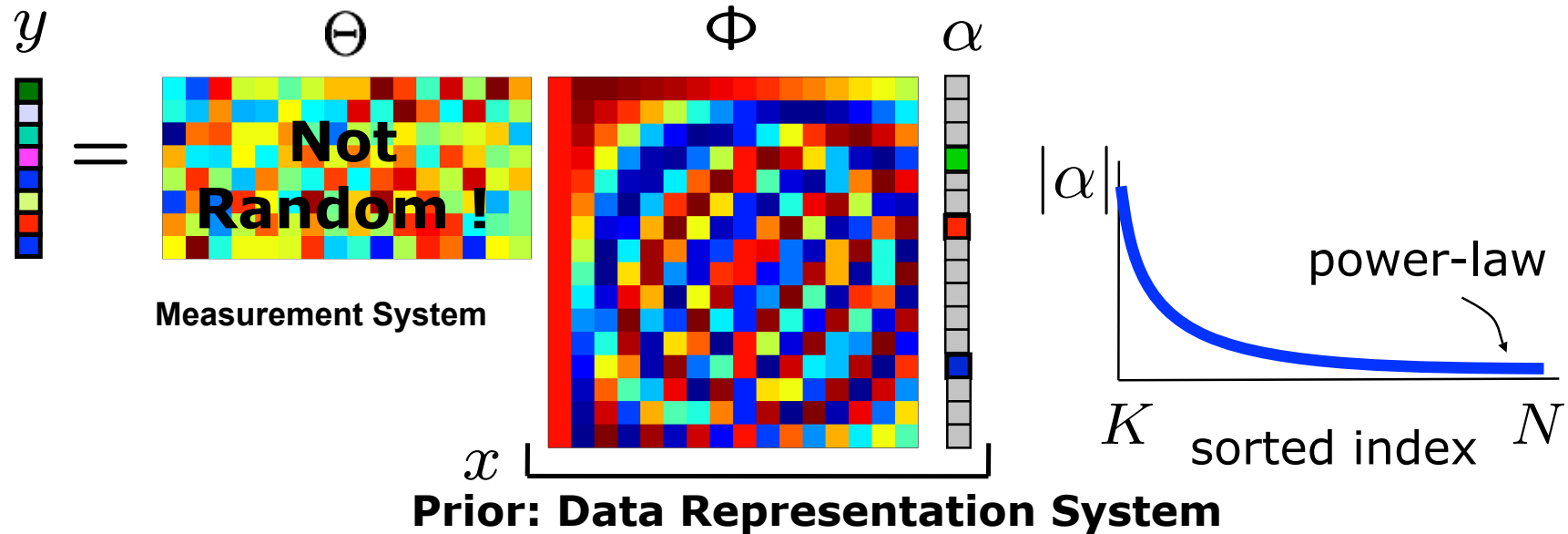


Reconstruction via non linear processing:

$$\min_x \|x\|_1 \quad \text{s.t.} \quad y = \Theta x$$

Soft Compressed Sensing Definition

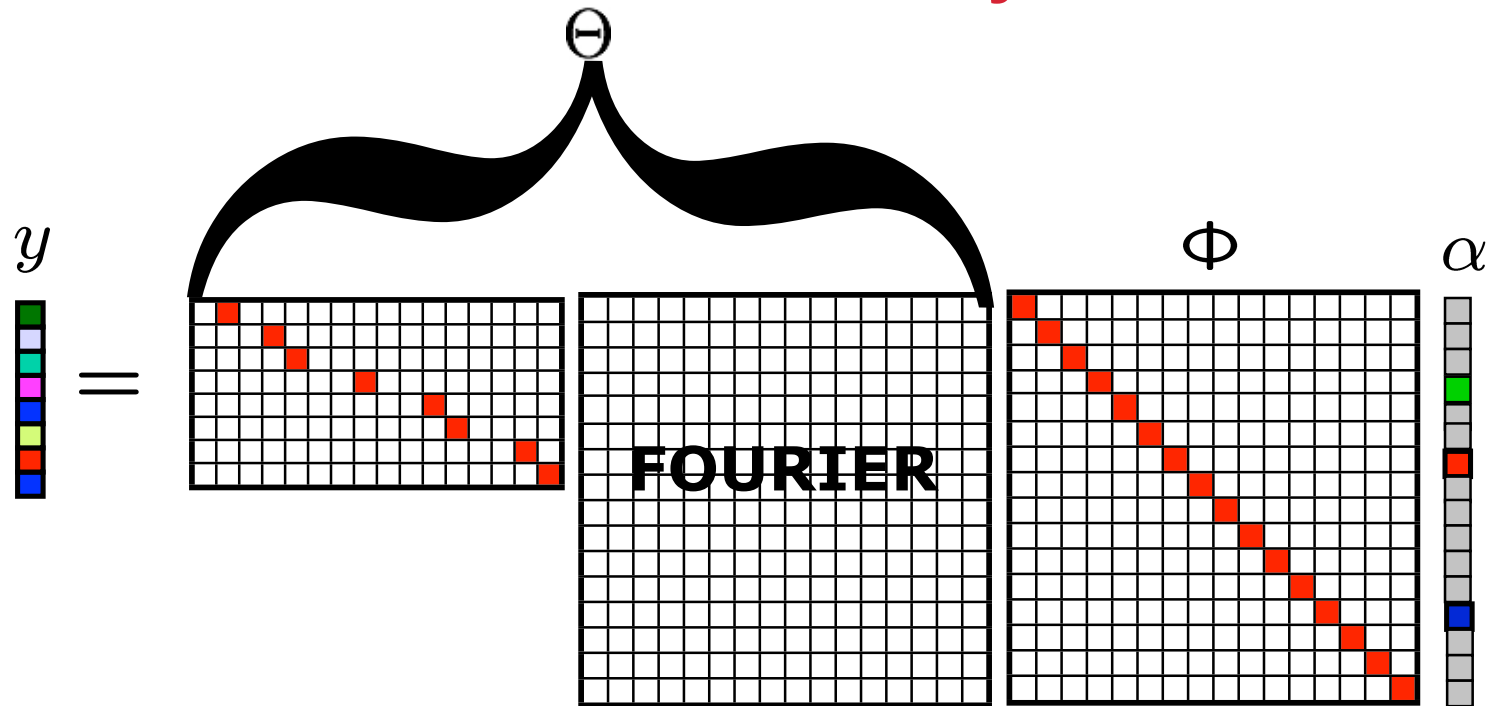
$$Y = \Theta X = \Theta \Phi \alpha$$



Mutual coherence:
$$\mu_{\Theta, \Phi} = \max_{i, k} \left| \left\langle \Theta_i, \Phi_k \right\rangle \right|$$

Mutual coherence the degree of similarity between the sparsity and measurement systems.

Radio-Interferometry



Measurement System

CLEAN Algorithm: $\Phi = \text{Id}$ (Hogbom, 1974)

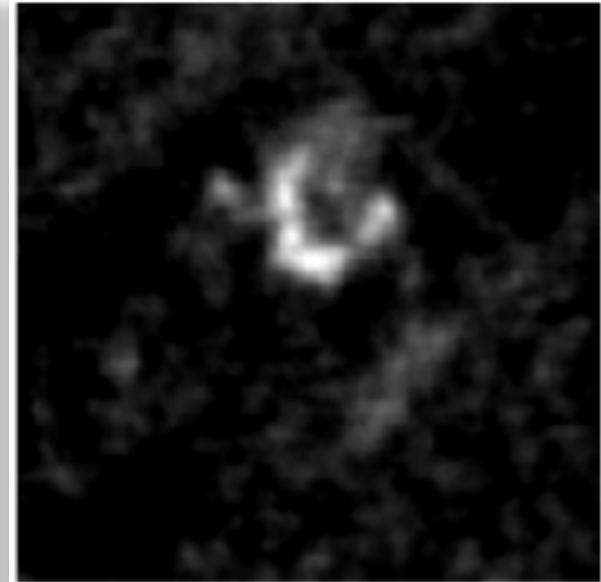
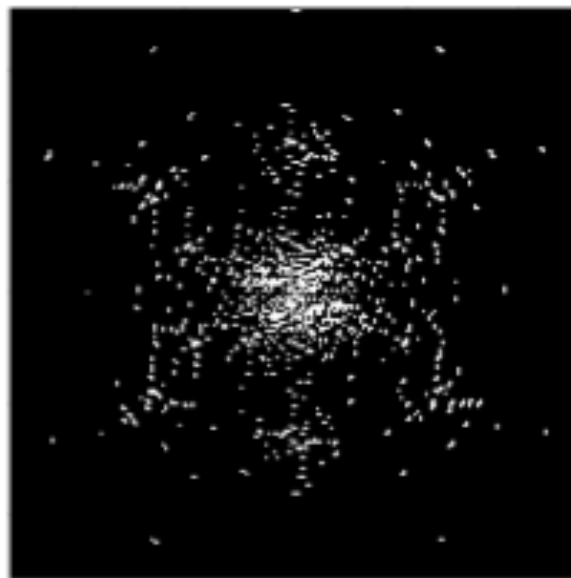
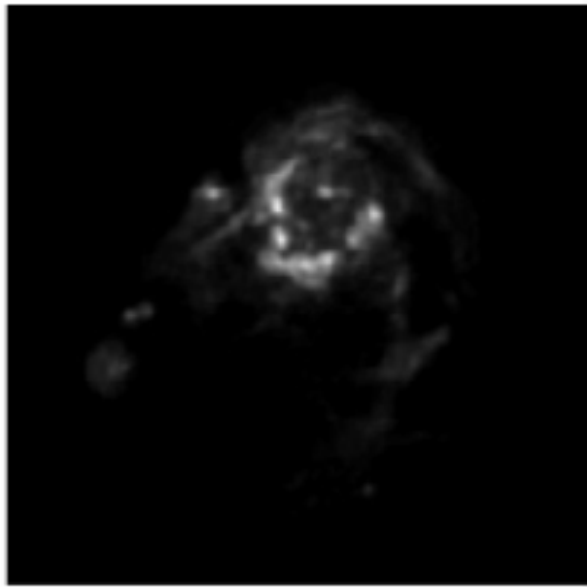
Wavelet Clean $\Phi = \text{Wavelet Transform}$ (Wakker, and Schwarz, 1988; Starck et al 1994)

\implies See (McEwen et al, 2011; Wenger et al, 2010; Wiaux et al, 2009; Cornwell et al, 2009; Suskimo, 2009; Feng et al, 2011).

CS-Radio Astronomy

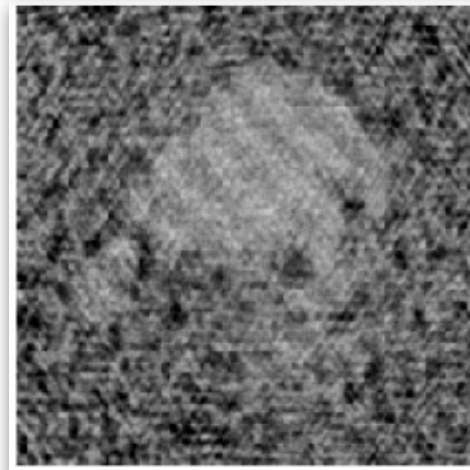
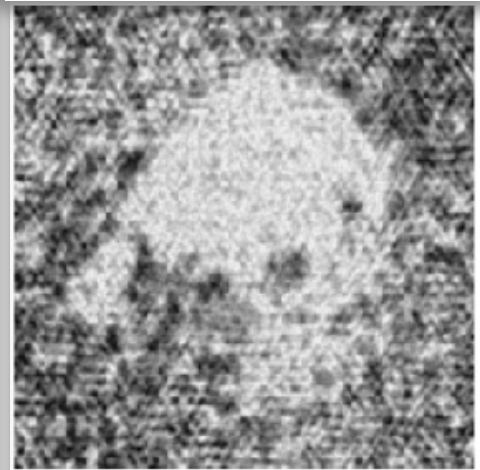
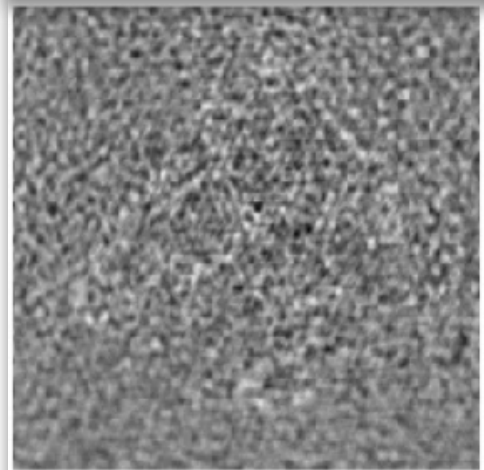
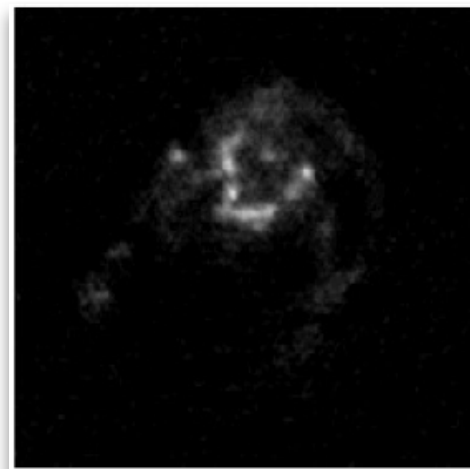
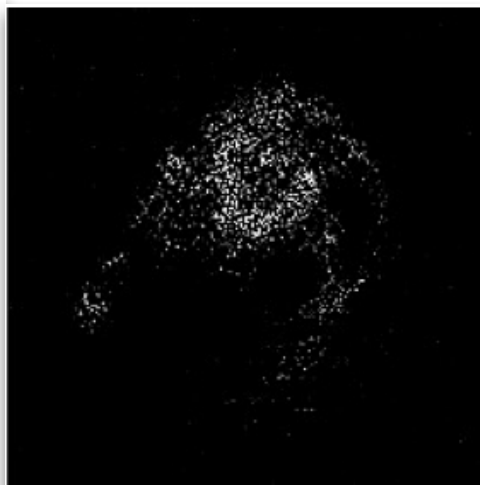
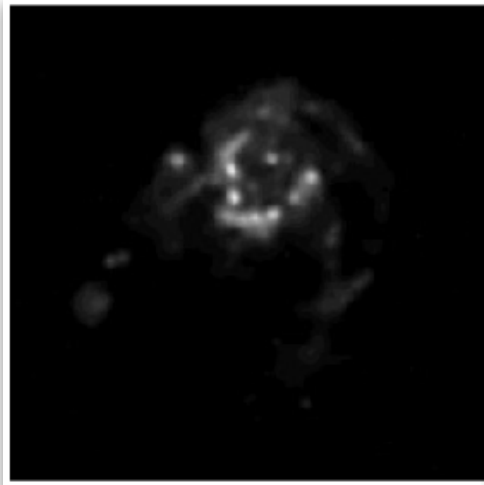
The Applications of Compressive Sensing to Radio Astronomy: I Deconvolution

Feng Li, Tim J. Cornwell and Frank De hoog, ArXiv:1106.1711, A&A, 528, A31,2011.



Australian Square Kilometer Array Pathfinder (ASKAP) radio telescope.

CS-Radio Astronomy



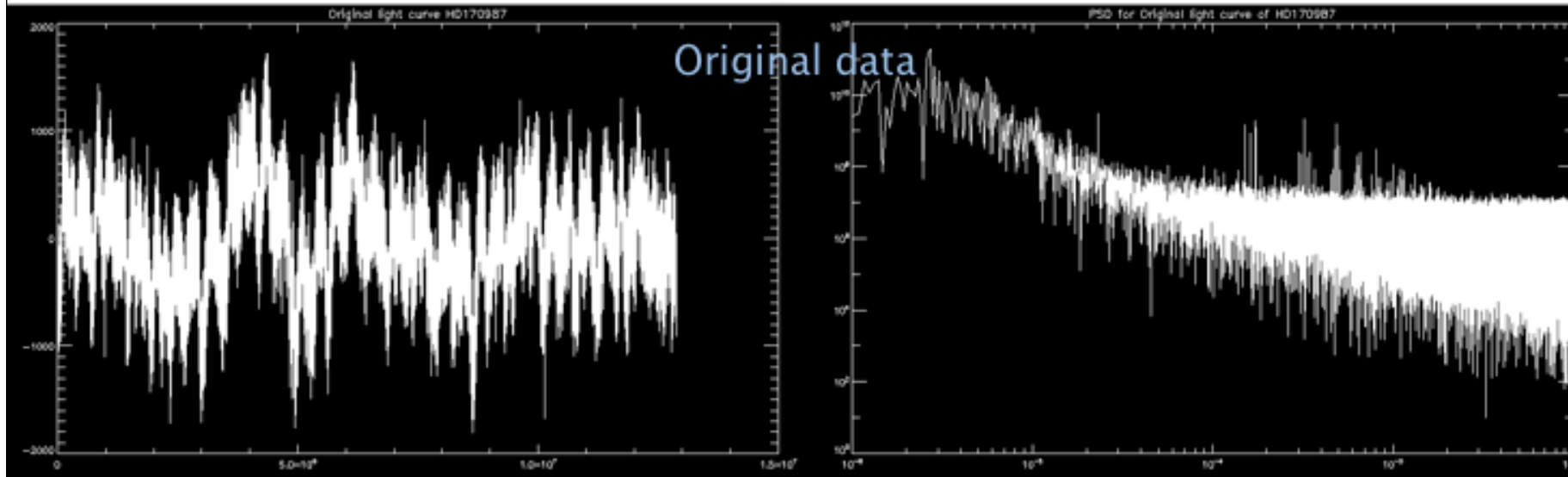
Hogbom CLEAN

MEM residual

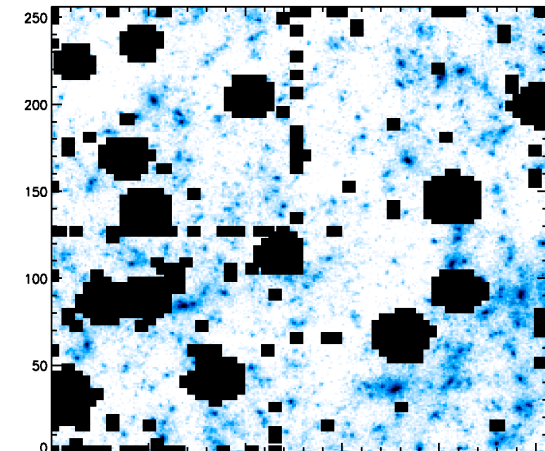
Missing Data

- Period detection in temporal series

COROT: HD170987

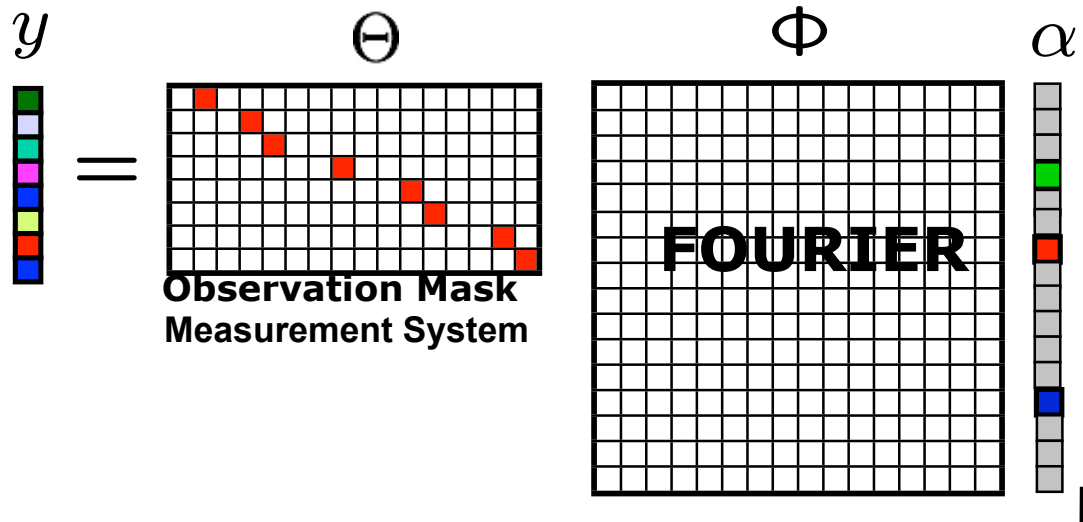


- Bad pixels, cosmic rays,
point sources in 2D images, ...

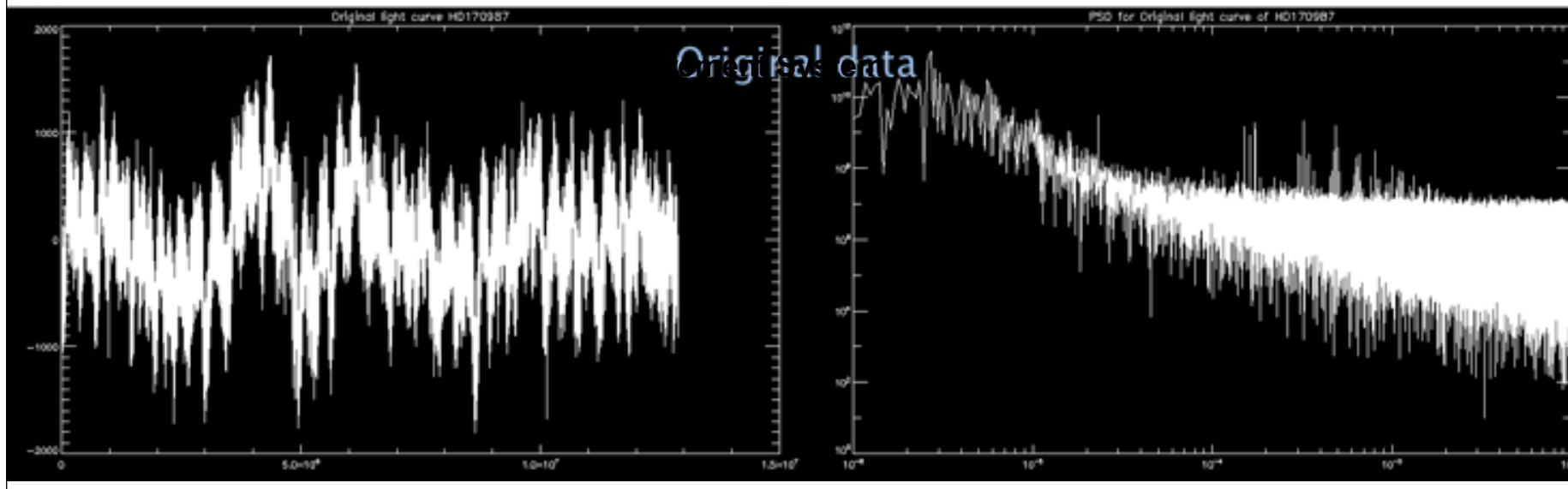


Missing Data

Period detection in temporal series

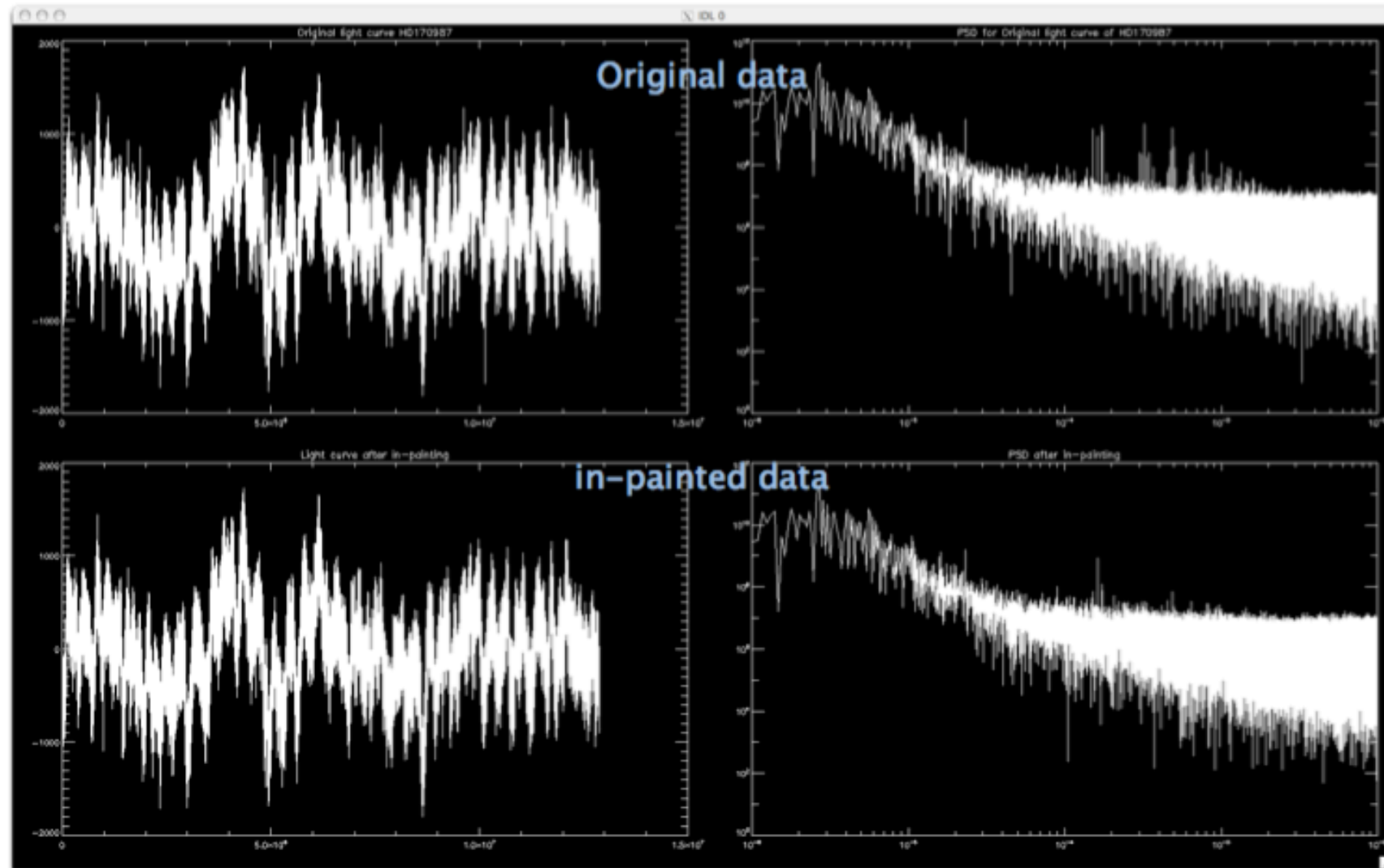


COROT: HD170987



COROT: HD170987 with in-painting

[arXiv:1003.5178](https://arxiv.org/abs/1003.5178)

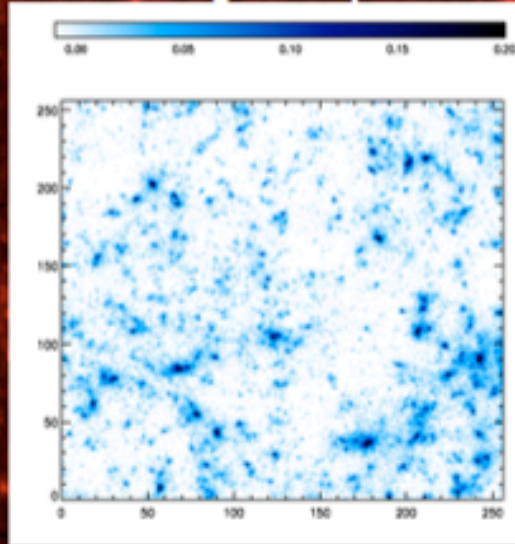


Inpainting :

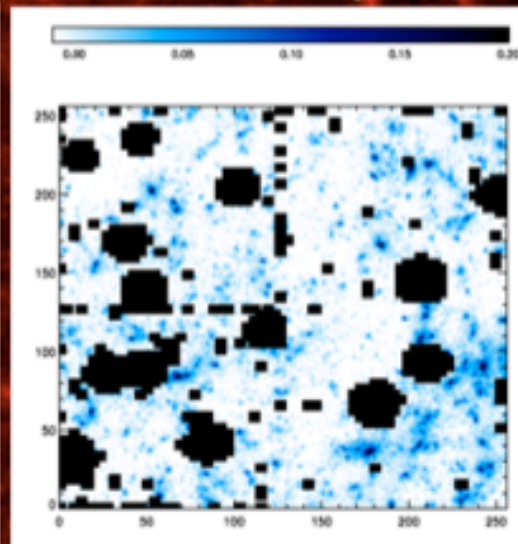
S. Pires, J.-L. Starck, A. Amara, R. Teyslier, A. Refregier and J. Fadilli, "FASTLens (FAst Statistics for weak Lensing) : Fast method for Weak Lensing Statistics and map making", MNRAS, 395, 3, pp. 1265-1279, 2009.



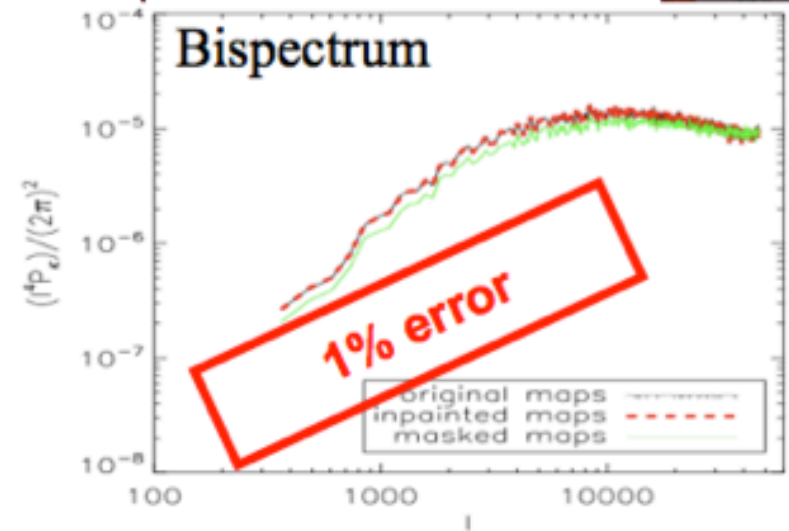
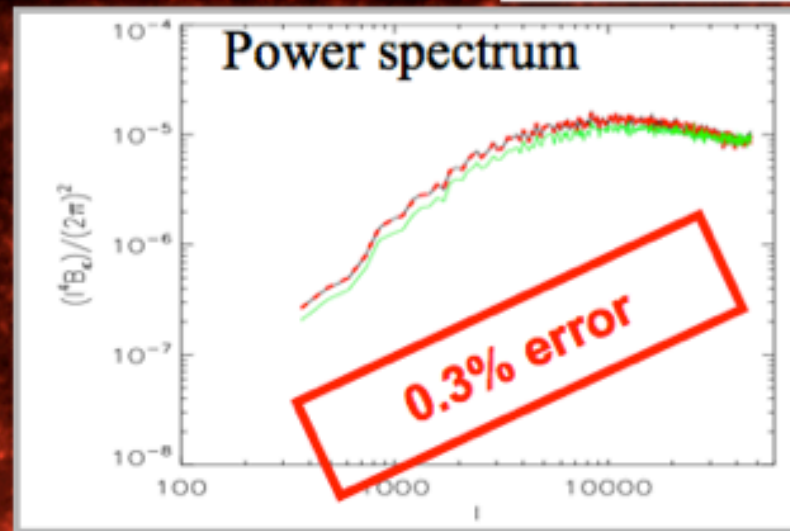
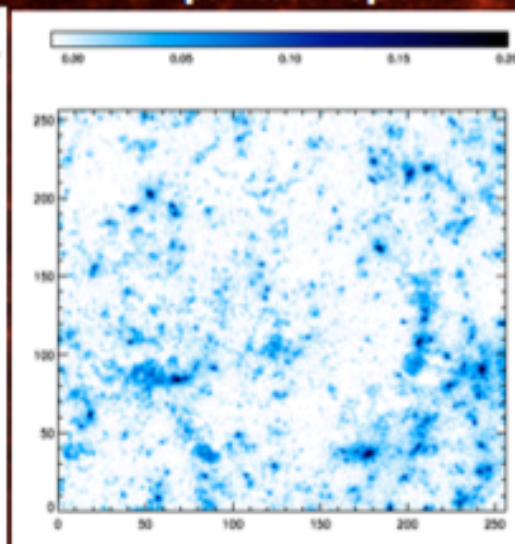
Original map



Masked map



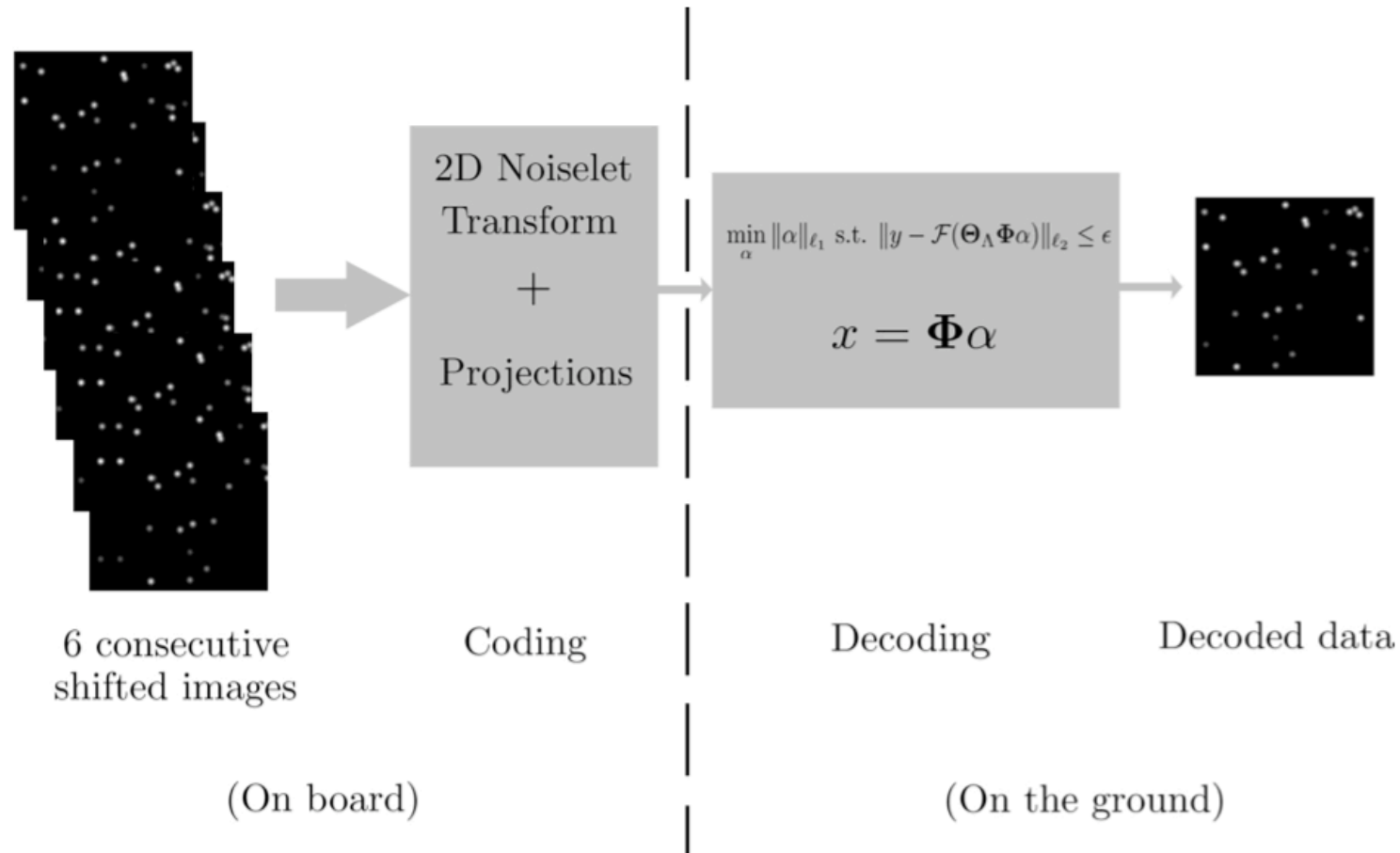
Inpainted map



Transferring Spatial Data to the Earth



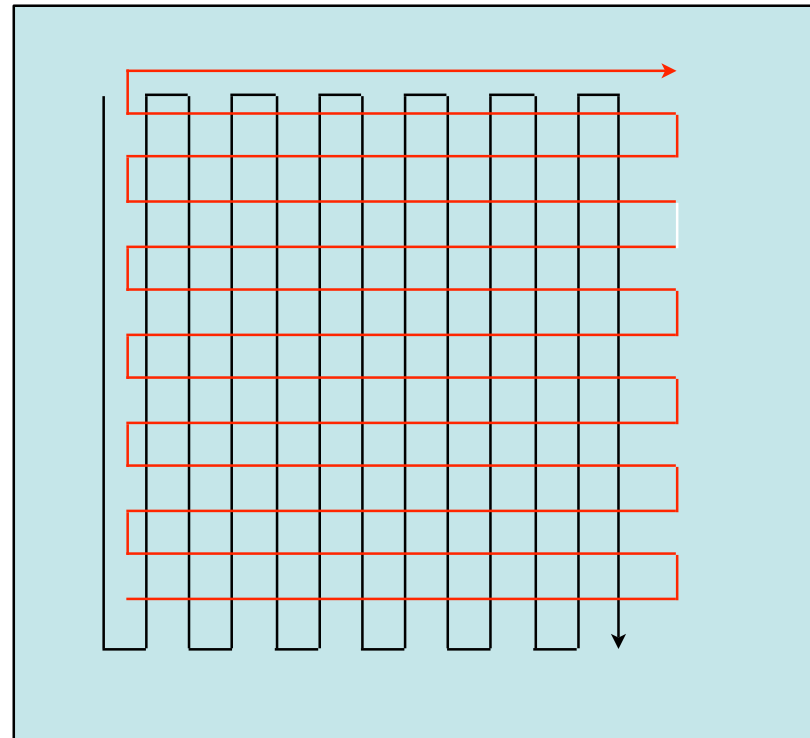
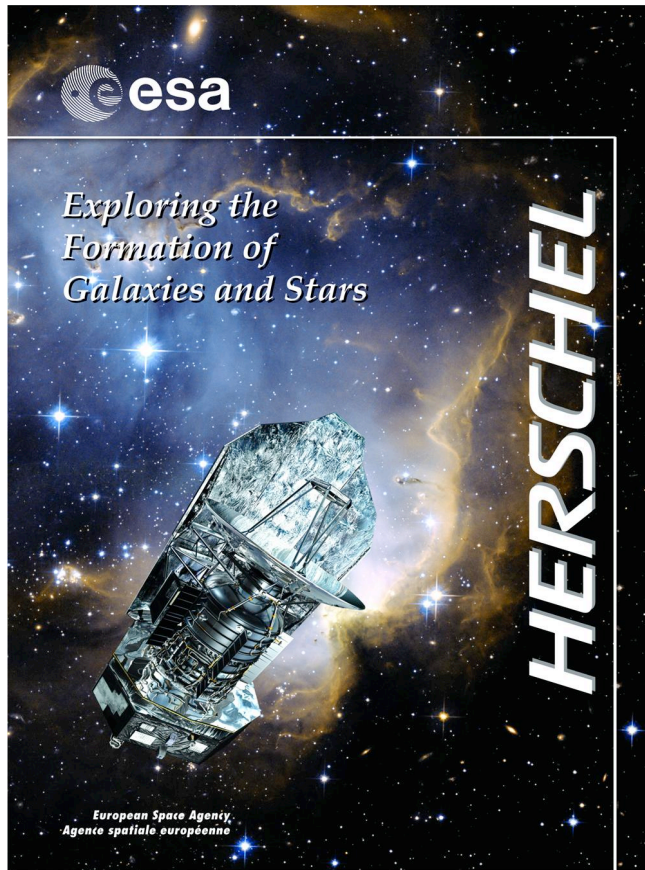
Bobin, J.-L. Starck, and R. Ottensamer, "Compressed Sensing in Astronomy", IEEE Journal of Selected Topics in Signal Processing, Vol 2, no 5, pp 718--726, 2008.



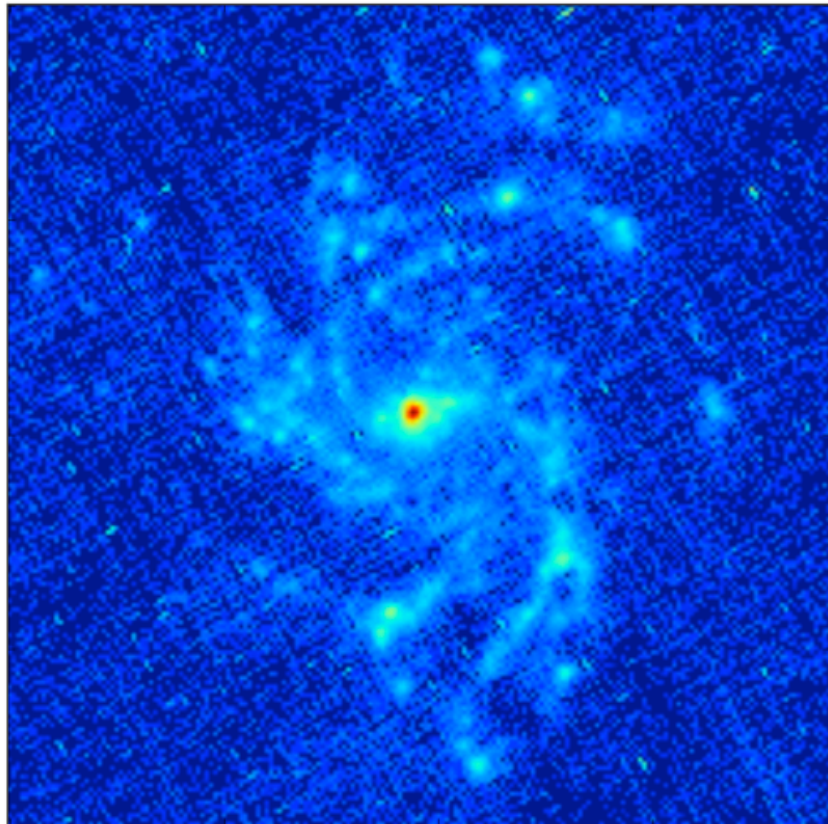
Transferring Data to the Earth

Observed Herschel Data During the Calibration Phase, November 2010, without any compression.

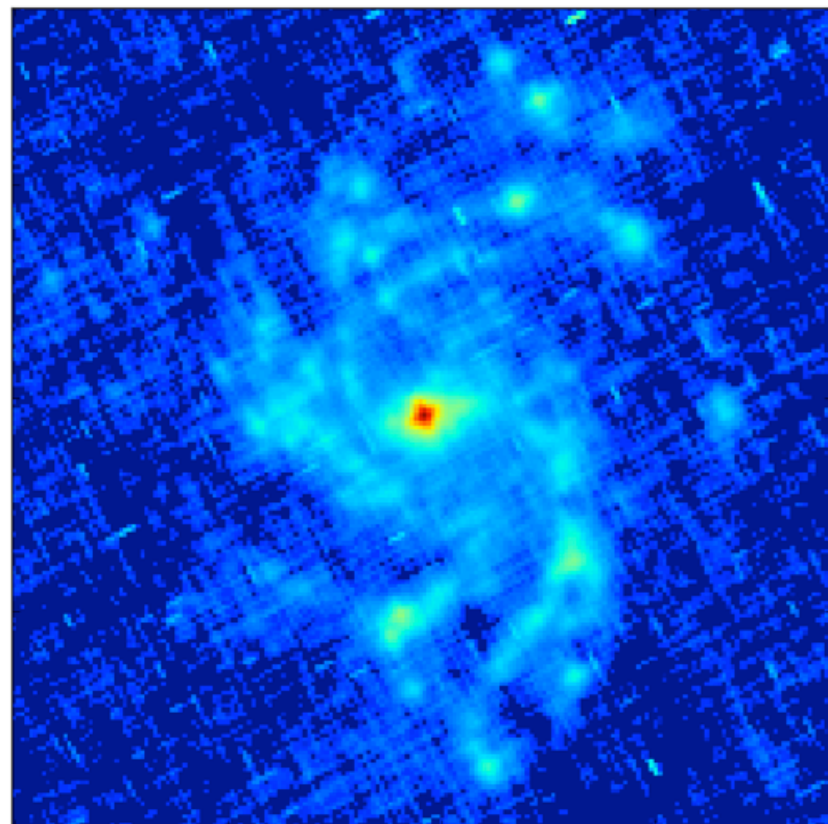
A scan (16 x 16 pixels at 40 Hz during 25 min each, we obtained 60000 images.



Map from Uncompressed Data



Official Pipeline Reconstruction: Averaging

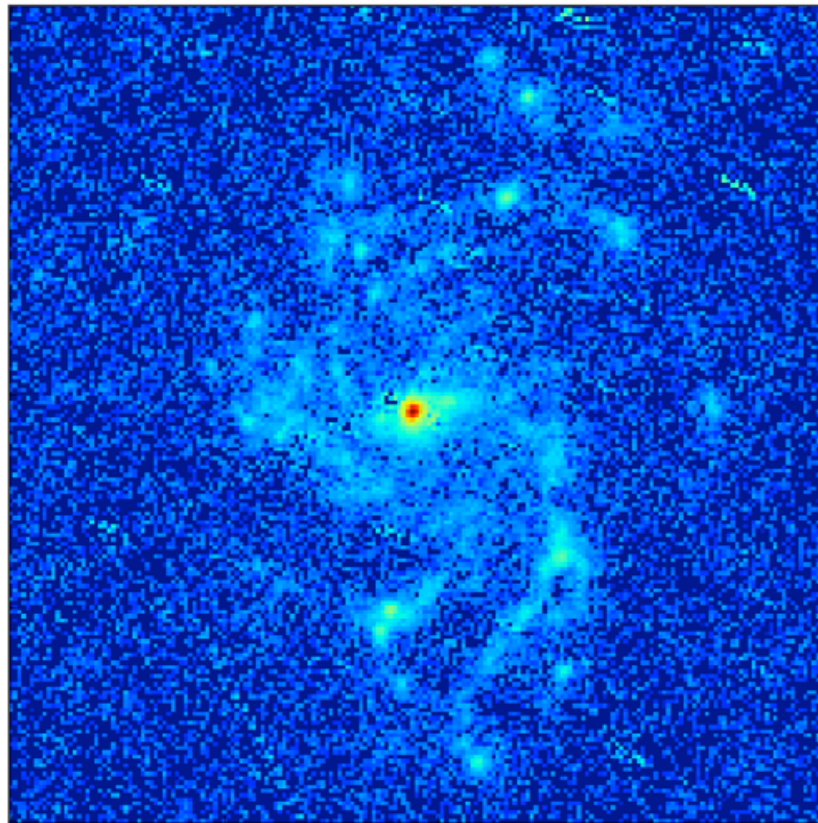




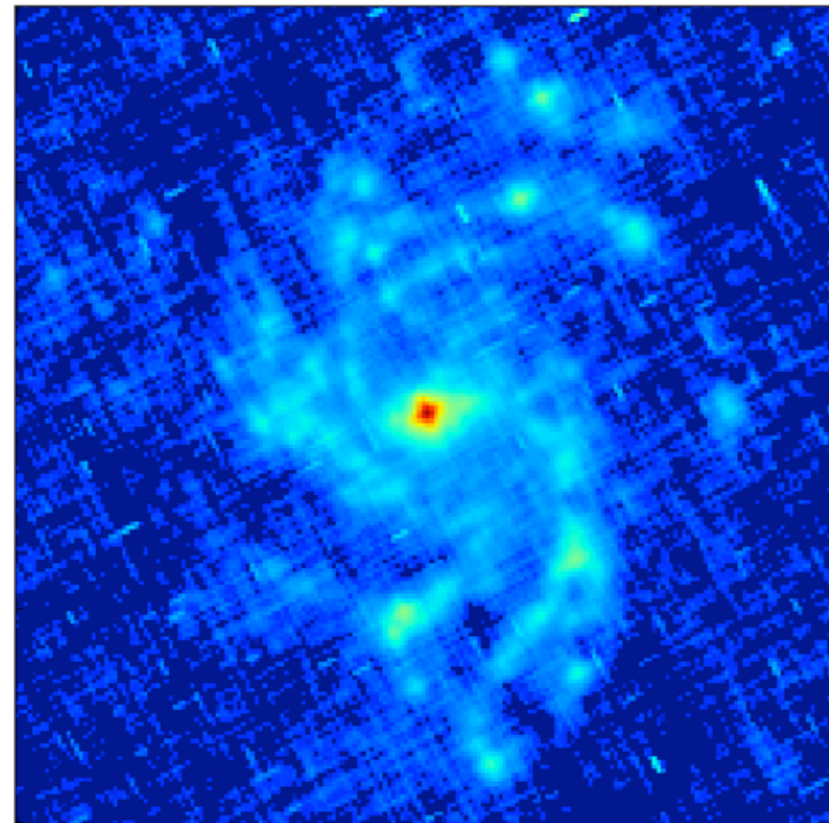
N. Barbey, M.Sauvage, J.-L. Starck, and R. Ottensamer, "[Feasibility and performances of compressed-sensing and sparse map-making with Herschel/PACS data](#)", **Astronomy and Astrophysics**, 527, 102 , 2011.



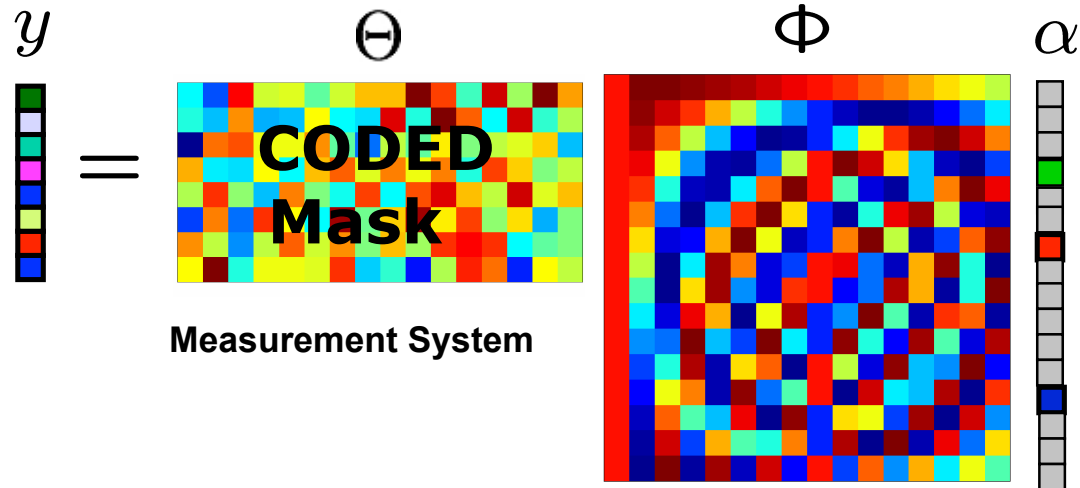
Compressed Sensing Reconstruction



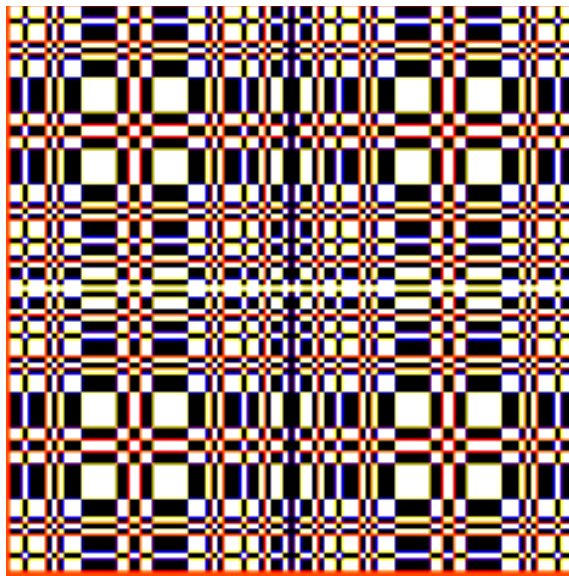
Official Pipeline Reconstruction: Averaging



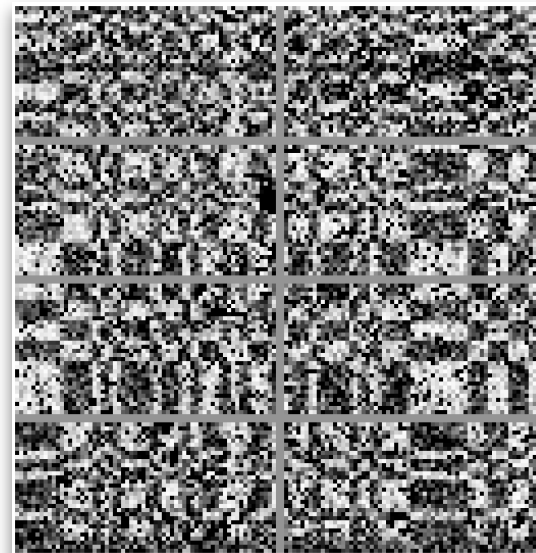
Gamma Ray Instruments (Integral) - Acquisition with coded masks



Measurement System



INTEGRAL/IBIS Coded Mask



Crab Nebula Integral Observation

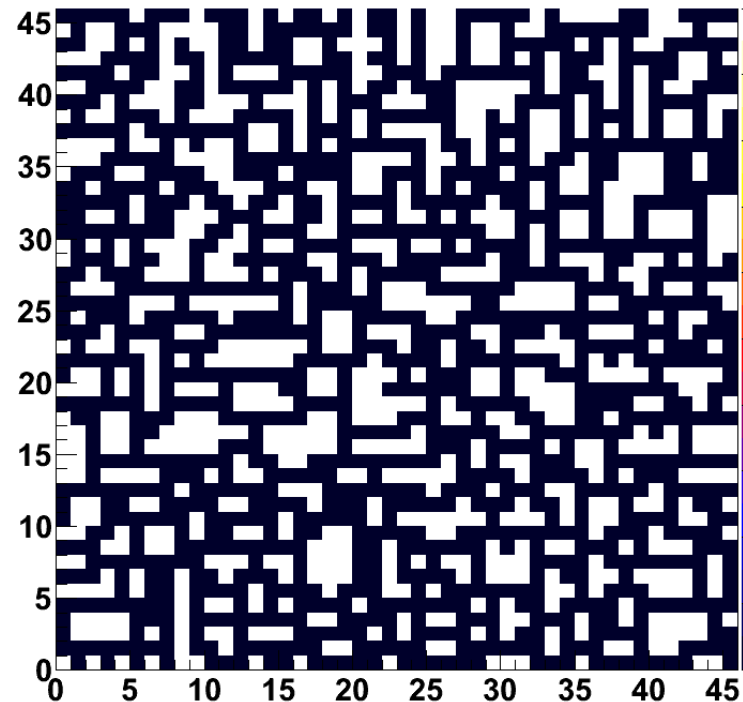
Courtesy I. Caballero, J. Rodriguez (AIM/Saclay)

SVOM (future French-Chinese Gamma-Ray Burst mission)

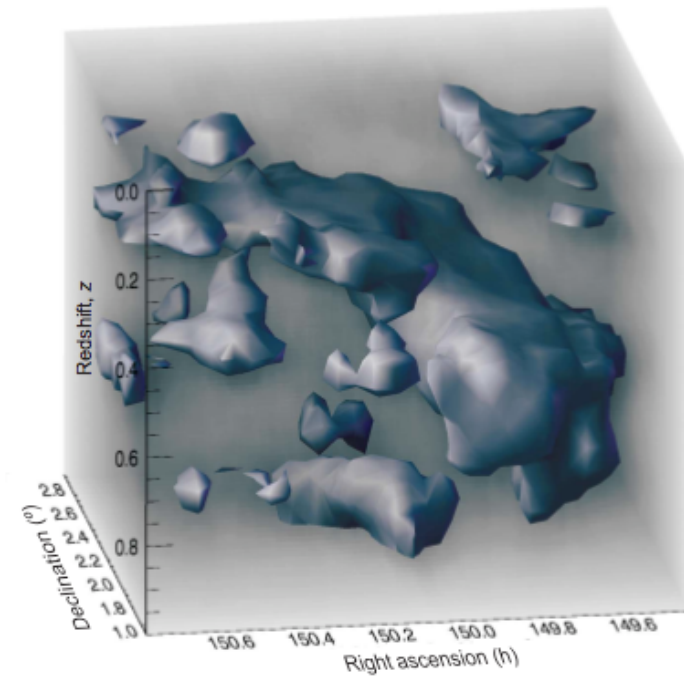
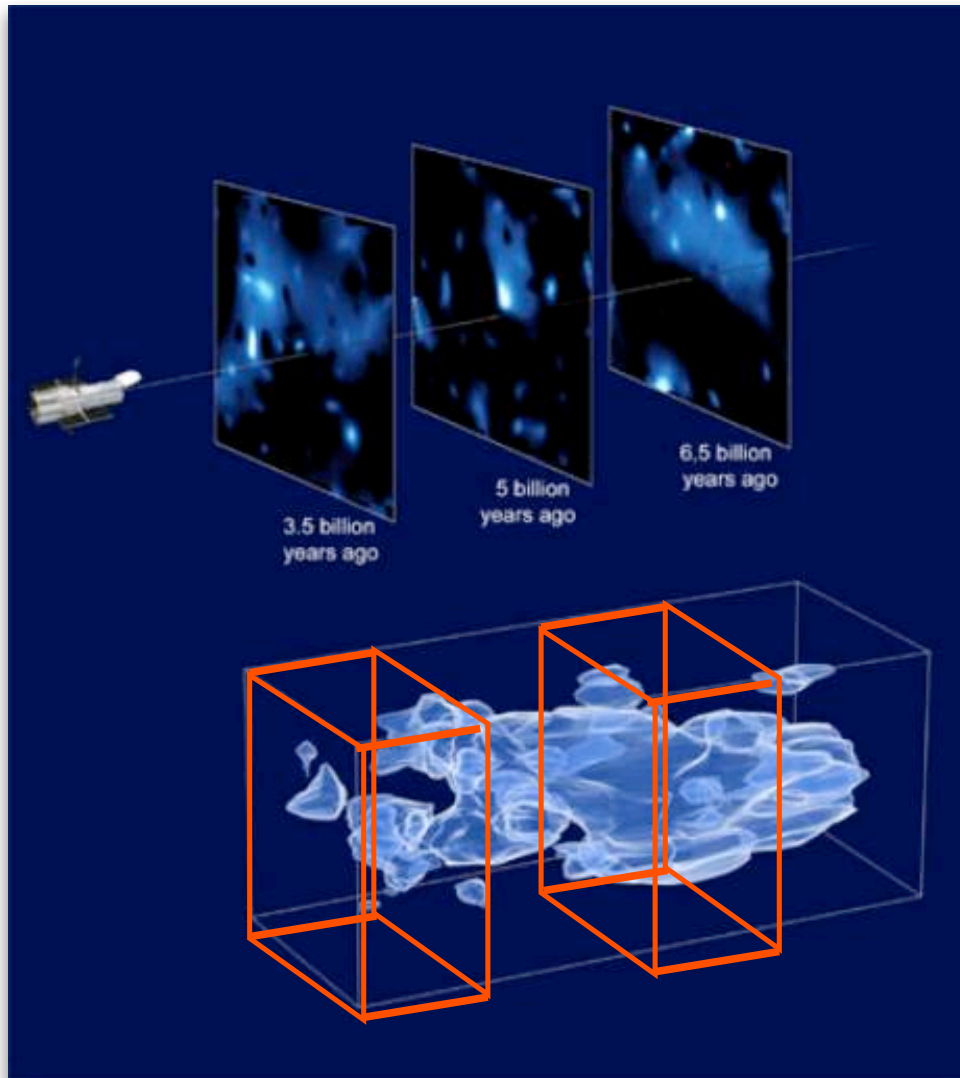
- **ECLAIRs** france-chinese satellite 'SVOM' (launch in 2014-2015)
Gamma-ray detection in energy range 4 - 120 keV
Coded mask imaging (at 460 mm of the detector plane)

Physical mask pattern

(46 x 46 pixels of 11.7 mm)



Pseudo-3D Weak Lensing



3D Weak Lensing

The convergence κ , as seen in sources of a given redshift bin, is the linear transformation of the matter density contrast, δ , along the line-of-sight (Simon et al 2009):

$$\kappa = Q\delta + N \quad \text{with} \quad \delta(r) \equiv \rho(r)/\bar{\rho} - 1$$

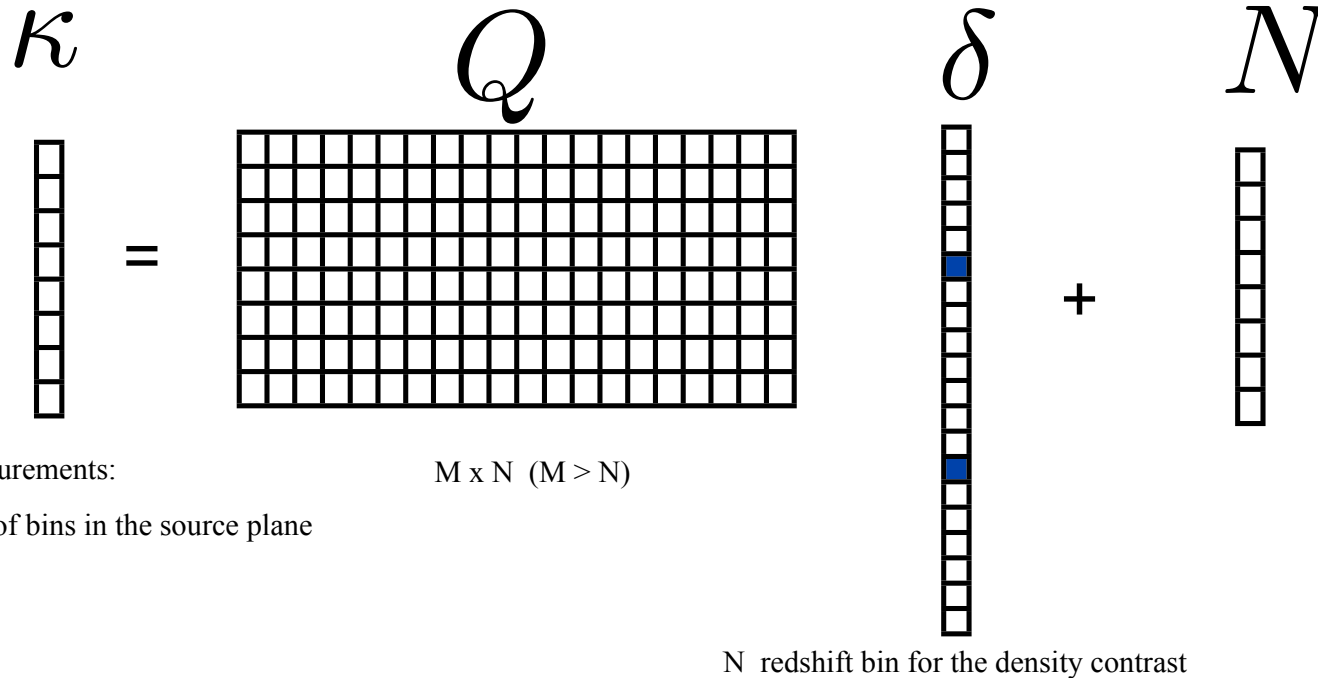
$$Q_{i\ell} = \frac{3H_0^2\Omega_M}{2c^2} \int_{w_\ell}^{w_{\ell+1}} dw \frac{\bar{W}^{(i)}(w)f_K(w)}{a(w)}, \quad \bar{W}^{(i)}(w) = \int_0^{w^{(i)}} dw' \frac{f_K(w-w')}{f_K(w')} \left(p(z) \frac{dz}{dw} \right)_{z=z(w')}$$

where H_0 is the hubble parameter, Ω_M is the matter density parameter, c is the speed of light, $a(w)$ is the scale parameter evaluated at comoving distance w , and

$$f_K(w) = \begin{cases} K^{-1/2} \sin(K^{1/2}w), & K > 0 \\ w, & K = 0 \\ (-K)^{-1/2} \sinh([-K]^{1/2}w) & K < 0 \end{cases},$$

gives the comoving angular diameter distance as a function of the comoving distance and the curvature, K , of the Universe.

3D Weak Lensing



δ is sparse.

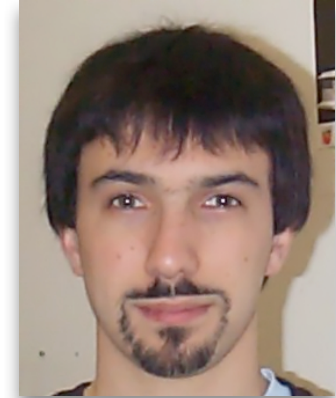
Q spreads out the information in δ along κ bins.

More unknown than measurements

3D Weak Lensing



Matter in the Universe as a Natural Compressed Sensing Operator

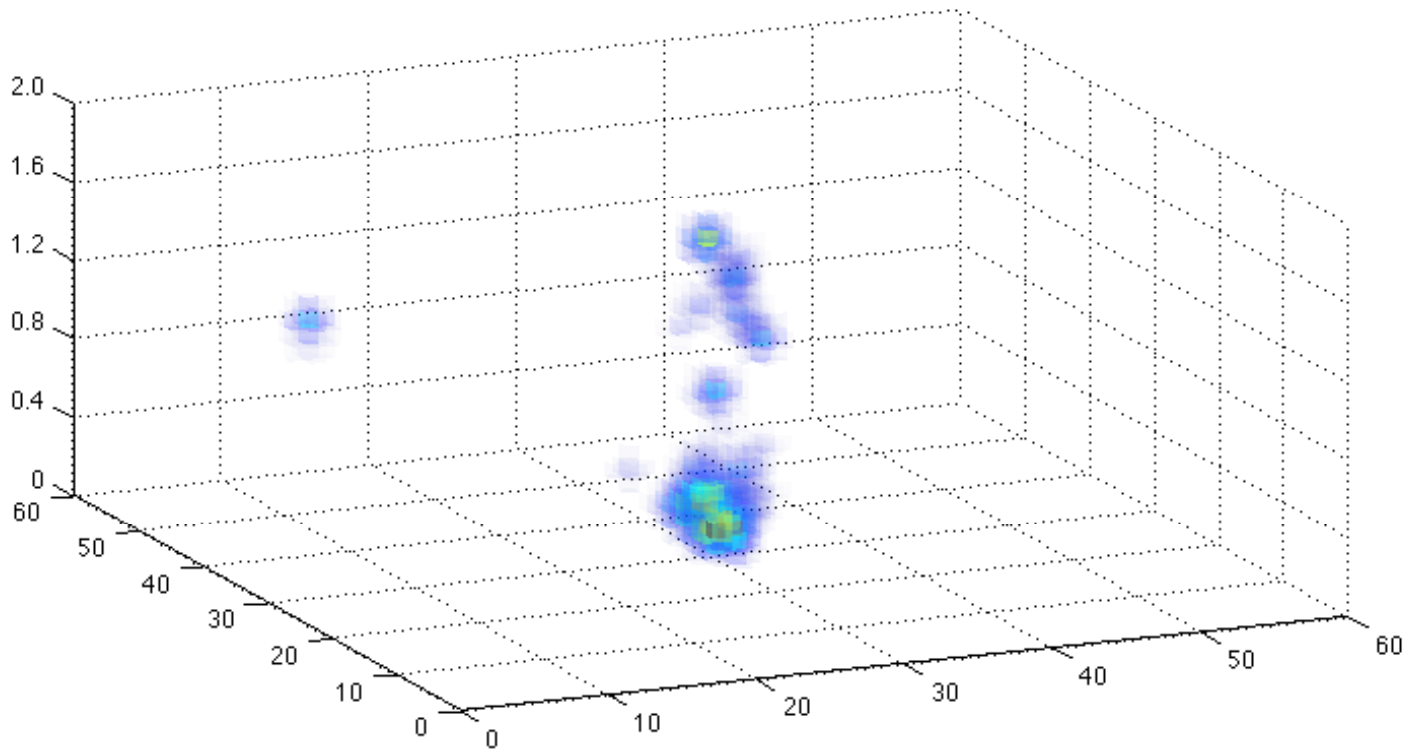


A. Leonard, F.-X. Dupe, J.-L. Starck, "A compressed sensing approach to 3D weak lensing", Astronomy and Astrophysics, [arXiv:1111.6478](https://arxiv.org/abs/1111.6478), A&A, in press.

$$\min_{\delta} \|\delta\|_1 \quad s.t. \quad \frac{1}{2} \|\kappa - Q\delta\|_{\Sigma^{-1}}^2 \leq \epsilon$$

Recent optimization method, based on proximal theory, such as Chambolle & Pock (2010) can be used to find the solution.

3D Weak Lensing



Reconstructions of two clusters along the line of sight, located at a redshift 0.2 and 1.0 (data binned into $N_{sp} = 20$ redshift bins, but aim to reconstruct onto $N_{lp} = 25$ redshift bins).

- Sparsity is very efficient for
 - Inverse problems (denoising, deconvolution, etc).
 - Inpainting
 - Component Separation.

- Compressed Sensing
 - New algorithms to process radio-interferometric data
 - New approaches to analyze data.
 - New instruments design.

- Perspectives
 - PLANCK component separation.
 - Euclid